

Incrementally Biasing Visual Search Using Natural Language Input

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The scenario

Search-and-rescue after a tornado



The scenario

Search-and-rescue after a tornado hits my room.



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- ▶ A robot is helping me clean up.

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- ▶ A robot is helping me clean up.
- ▶ But there are hundreds of objects in this room.
- ▶ Visual search is a notoriously hard problem.

The scenario

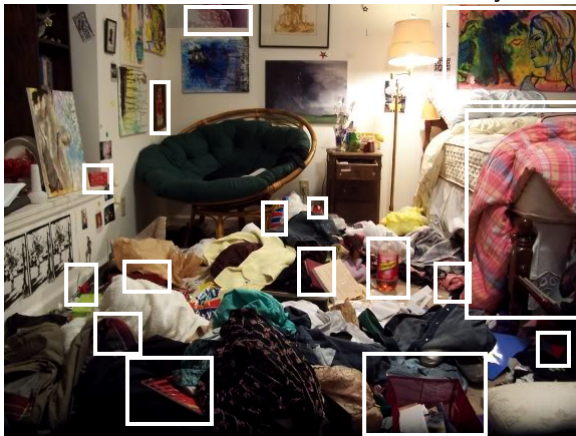
Search-and-rescue after a tornado hits my room.



There's a book and it's red...

The scenario

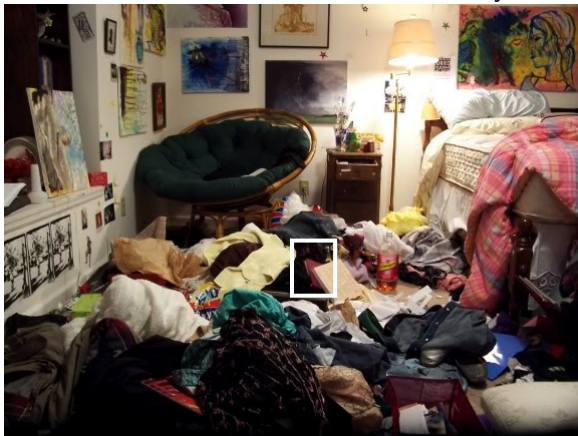
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There's a **book** and it's red...

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- ▶ derive from natural language top-down constraints on vision;
- ▶ allow vision to use easy tasks to help with hard tasks.

Previous Research

- ▶ Recent work on constraining vision with top-down cues has not drawn these cues from natural language (c.f., Choi et al. [CBL⁺04], Frintrop et al. [FBR05], Navalpakkam et al. [NI06]).

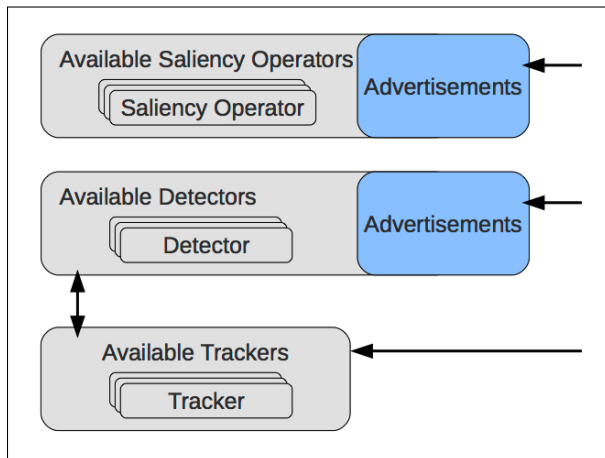
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- ▶ We want to collect attentional cues from natural language to reduce the complexity of vision tasks.

Vision



Saliency

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- ▶ height - distance between a point and a supporting surface below
- ▶ location - saliency decreases in the form of a Gaussian from the selected image border or image center

Measuring the Cost of Visual Search

Different types of saliency operators have different computational costs.

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Measuring the Cost of Visual Search

Different types of saliency operators have different computational costs.

$$C(S) = c_p * n_p \quad (1)$$

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- ▶ n_p : number of points

Measuring the Cost of Visual Search

Different types of saliency operators have different computational costs.

$$C(S) = c_p * n_p + c_f \quad (1)$$

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- ▶ c_f : fixed costs; depends only on saliency type

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Incremental Vision



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Incremental Vision



Incremental Vision



- Non-incremental

Incremental Vision



- ▶ Non-incremental
- ▶ Incremental

Incremental Vision



- ▶ Non-incremental
- ▶ Incremental

Processing Order

- ▶ Parallel

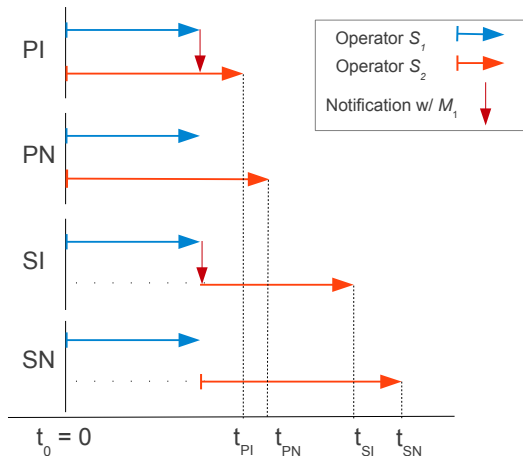
Processing Order

- ▶ Parallel
- ▶ Sequential

Processing Order

- ▶ Parallel
- ▶ Sequential
- ▶ Staggered

Four saliency operator configurations and their relative times to completion



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- ▶ With attention: Begins with objects containing the most salient points

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2. Once a visual search has begun, we send all descriptors to vision immediately.
3. We end the visual search when we find some word that cannot be part of it.

Incremental Processing of Linguistic Input



can you see
(vision waiting)

Incremental Processing of Linguistic Input



can you see **a**
(search started)

Incremental Processing of Linguistic Input



can you see a **tall**
(constraint: tall)

Incremental Processing of Linguistic Input



can you see a tall red
(constraint: red)

Incremental Processing of Linguistic Input



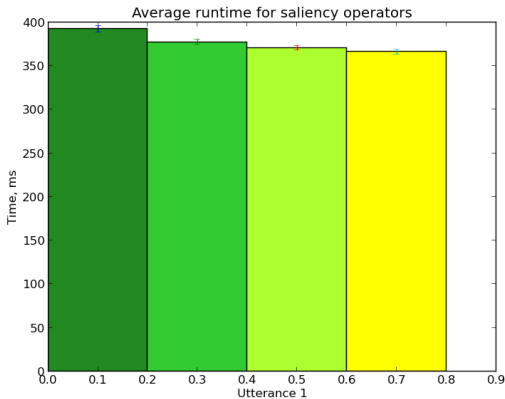
can you see a tall red **object**

Incremental Processing of Linguistic Input



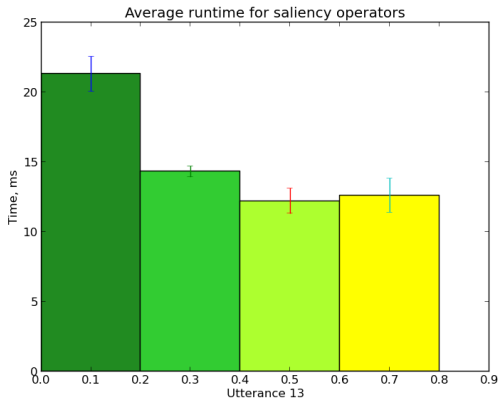
can you see a tall red object at left
(constraint: left)
(results returned)

Experimental results.



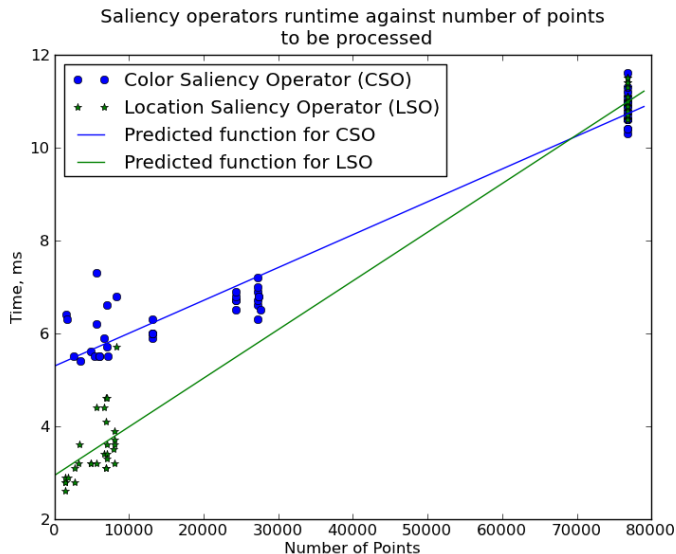
“The short green top object”
Left to Right: SN, SI, PN, PI

Experimental results.



“The red right object”
Left to Right: SN, SI, PN, PI

Experimental results.



Color and location saliency operator runtime vs. n_p .

Experimental Design

- ▶ Seven scenes each contained 11 objects for each of which a uniquely-identifying verbal description containing one to four descriptive or locational constraints (e.g., *red*, *tall*, *right*, *front*) was formulated.

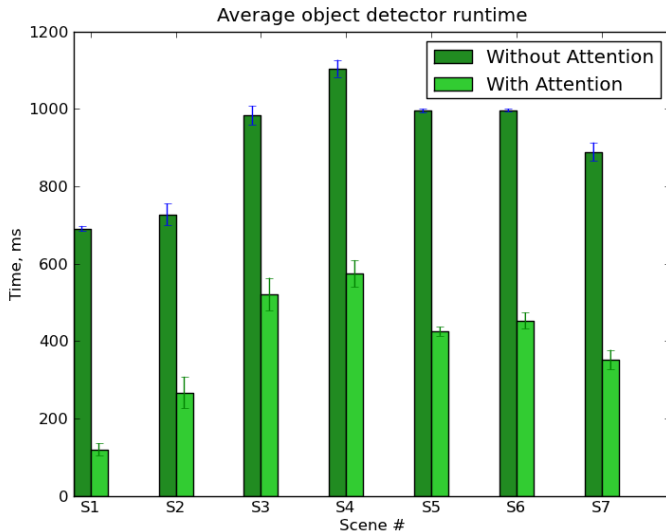
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- ▶ As each scene was viewed, each associated description was presented incrementally (as in spoken natural language) 10 times.

Experimental results.



Average object detector runtime across scenes.

Future Work

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- ▶ The reverse direction, using visually-acquired information to constrain natural language interpretation, needs to be explored.

Acknowledgements

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References

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Thanks for your attention!
...Questions?